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3200 Series PID Temperature Controllers ACS Custom Manual Issue 1.0

3216 Controllers

Issue 1 of this Handbook applies to software versions 2.09 and above for PID controller and includes:

Remote Setpoint Input Option RCL

Programmer Cycles

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1. Installation and Basic Operation

1.1 What Instrument Do I Have?

Thank you for choosing this 3200 series Temperature Controller/Programmer.

A universal input accepts various thermocouples, RTDs or process inputs. Up to three 3216 outputs can be configured for control, alarm or re-transmission purposes. Digital communications and a current transformer input are available as options.

The controller may have been ordered to a hardware code only or pre-configured using an optional 'Quick Start' code.

The label fitted to the side of the sleeve shows the ordering code that the controller was supplied to.

The last two sets of five digits show the Quick Code.

If the Quick Code shows *****/***** the controller was supplied with default parameters and will need to be configured when it is first switched on.

This Manual takes you through all aspects of installation, wiring, configuration and use of the controller. Dimensions General views of the controllers are shown below together with overall dimensions.

3216



Π

1.2 What Firmware Do I Have?

The startup screen will display the firmware version immediately on power up. Version 2.09 is the standard controller that is capable of communicating Modbus communications protocal. Version 2.50 is the standard controller that is capable of communicating SPI communications protocol.





Firmware V2.50 (SPI)



What Instrument Do I Have?

Order Code

1	2	3	4	5	6	7	8	9	10	11	12	13	14
3216													

1. Model No.	
1/16 DIN size	3216

2. Function	
Controller	CC
Programmer	CP
valve controller	VC
Valve programmer	VP

3. Power Supply	
24Vac/dc	VL
100-240Vac	VH

4. Outputs 1 and 2 3216					
OP1	OP2				
х	Х	Х	Х		
L	Х	Х	Х		
L	R	Х	Х		
R	R	Х	Х		
L	L	Х	Х		
L	D	Х	Х		
D	D	Х	Х		
D	R	Х	Х		
L	Т	Х	Х		
Т	Т	Х	Х		

Triac not available with low voltage supply option.

L = Logic; R = Relay;

D = DC ⁽¹⁾; T = Triac

5. AA Relay (OP4)	
Disabled	Х
Relay (Form C)	R
6. Options	
Not fitted	XXX
RS485 & Digital input A	4XL
RS232 & Digital input A	2XL
RS485, CT & Dig in A	4CL
RS232, CT & Dig in A	2CL
Digital input A	XXL
CT & Digital input A	XCL
Remote SP and Logic IP	RCL

7. Fascia colou	ır/type
Green	G
Silver	S
Wash down fascia (2)	W

8/9 Product/Manual Language					
English	ENG				
French	FRA				
German	GER				
Italian	ITA				
Spanish	SPA				

10. Extended Warranty			
Standard	XXXXX		
Extended	WL005		

11. Certificates				
None	XXXXX			
CERT1	Cert of conformity			
CERT2	Factory calibration			
12. Custom Label				
XXXXX None				

13. Specials Number				
XXXXXX	None			
RES250	250Ω; 0-5Vdc OP			
RES500	500Ω ; 0-10Vdc OP			

2. Wiring



2.1 Terminal Layout 3216 Controller



3. Panel Layout

ALM Alarm active (Red)

OP1 lit when output 1 is ON (normally heating)

OP2 lit when output 2 is ON (normally cooling)

OP3 lit when output 3 is ON

OP4 lit when output 4 relay is ON (normally alarm)

SPX Alternative setpoint in use (e.g. setpoint 2)

REM Remote digital setpoint. Also flashes when digital communications active

RUN Timer/programmer running

RUN (flashing) Timer/programmer in hold

MAN Manual mode selected

Operator Buttons:-

From any display - press to return to the HOME display

Press to select a new parameter. If held down it will continuously scroll through parameters.

Press to decrease a value

Press to increase a value

3.1.2 Alarms

Up to four process alarms may be configured. Each alarm can be configured for:-

Full Scale Low	The alarm is shown if the process value falls below a set threshold
Full Scale High	The alarm is shown if the process value rises above a set threshold
Deviation Low	The alarm is shown if the process value deviates below the setpoint by a set threshold
Deviation High	The alarm is shown if the process value deviates above the setpoint by a set threshold
Deviation Band	The alarm is shown if the process value deviates above and below the setpoint by a set threshold

If an alarm is not configured it is not shown in the list of level 2 parameters, section 5.3

Additional alarm messages may be shown such as CONTROL LOOP BROKEN. This occurs if the controller does not detect a change in process value following a change in output demand after a suitable delay time.

Another alarm message may be INPUT SENSOR BROKEN (5br). This occurs if the sensor becomes open circuit; the output level will adopt a 'SAFE' value which can be set up in Operator Level 2.



3.1.1 To Set The Target Temperature.

From the HOME display:-



The new setpoint is entered when the button is released and is indicated by a brief flash of the display.

3.1.3 Alarm Indication

If an alarm occurs, the red ALM beacon will flash. A scrolling text message will describe the source of the alarm. Any output (usually a relay) attached to the alarm will operate. An alarm relay can be configured using the Quick Start Codes to be energised or de-energised in the alarm condition. It is normal to configure the relay to be de-energised in alarm so that an alarm is indicated if power to the controller fails.

Press and (ACK) together to acknowledge

If the alarm is still present the ALM beacon will light continuously otherwise it will go off.

The action which takes place depends on the type of alarm configured:-

Non latching	A non latching alarm will reset itself when the alarm condition is removed. By default alarms are configured as non-latching, de- energised in alarm.
Auto Latching	An auto latching alarm requires acknowledgement before it is reset. The acknowledgement can occur BEFORE the condition causing the alarm is removed.
Manual Latching	The alarm continues to be active until both the alarm condition is removed AND the alarm is acknowledged. The acknowledgement can only occur AFTER the condition causing the alarm is removed.

By default alarms are configured as non-latching, deenergised in alarm.

3.1.4 Auto, Manual and Off Mode

The controller can be put into Auto, Manual or Off mode – see next section.

Auto mode is the normal operation where the output is adjusted automatically by the controller in response to changes in the measured temperature.

In Auto mode all the alarms and the special functions (auto tuning, soft start, timer and programmer) are operative

Manual mode means that the controller output power is manually set by the operator. The input sensor is still connected and reading the temperature but the control loop is 'open'.

In manual mode the MAN beacon will be lit, Band and deviation alarm are masked, the auto-tuning timer and programmer functions are disabled.

The power output can be continuously increased or decreased using the \bigtriangleup or \bigtriangledown buttons.

Manual mode must be used with care. The power level must not be set and left at a value that can damage the process or cause over-heating. The use of a separate 'over-temperature' controller is recommended.

Off mode means that the heating and cooling outputs are turned off. The process alarm and analogue retransmission outputs will, however, still be active while Band and deviation alarm will be OFF.

3.1.5

To Select Auto, Manual or Off Mode

Press and hold ______ and _____ (Mode) together for more than 1 second.

This can only be accessed from the HOME display.

 Huto' is shown in the upper display. After 5 seconds the lower display will scroll the longer description of this parameter. ie 'loop mode – auto manual off'



again to select 'DFF'. This is shown in the upper display.3. When the desired Mode is selected, do

2.

Press

not push any other button. After 2 seconds the controller will return to the HOME display.

to select 'mAn'. Press

- 4. If **OFF** has been selected, **DFF** will be shown in the lower display and the heating and cooling outputs will be off
- 5. If manual mode has been selected, the **MAN** beacon will light. The upper display shows the measured temperature and the lower display the demanded output power.
- The transfer from Auto to manual mode is 'bumpless'. This means the output will remain at the current value at the point of transfer. Similarly when transferring from Manual to Auto mode, the current value will be used. This will then slowly change to the value demanded automatically by the controller.
- To manually change the power output, press v or
 to lower or raise the output. The output power is continuously updated when these buttons are pressed
- 7. To return to Auto mode, press $_$ and $_$ to select ' $\exists \mu \perp \mu$ '.

Fild

4. Operator Level 1

4.1.1 Level 1 Operator Parameters

A minimal list of parameters are available in operator Level 1 which is designed for day to day operation. Access to these parameters is not protected by a pass code.

Press to step through the list of parameters. The mnemonic of the parameter is shown in the lower display. After five seconds a scrolling text description of the parameter appears.

The value of the parameter is shown in the upper display. Press or to adjust this value. If no key is pressed for 30 seconds the controller returns to the HOME display

The parameters that appear depend upon the functions configured. They are:-

Home List

Parameter Mnemonic	Scrolling Display and Description	Alterability
WRK.OP	WORKING OUTPUT The active output value	Read only. Appears when the controller is in AUTO or OFF mode.
		In a motorised valve controller (option VC or VP) this is the 'inferred' position of the valve
A.TUNE	AUTO TUNE Activate Auto Tune Of PID Loop.	Alterable
SP1	SETPOINT 1	Alterable
SP2	SETPOINT 2	Alterable
T.REMN	TIME REMAINING Time to end of set period	Read only 0:00 to 99.59 hh:mm or mm:ss
DWELL	SET TIME DURATION Timer set time	Alterable. Only shown if timer (not programmer) configured.
DEC.P	DECIMAL POINT	Read only
UNITS	DISPLAY UNITS	Read Only
PB	PROPORTIONAL BAND	Alterable
TI	INTEGRAL TIME	Alterable
TD	DERIVATIVE TIME	Alterable
R2G	RELATIVE COOL GAIN	Read Only
OP.HI	OUTPUT HIGH LIMIT	Read Only
ADDR	COMMS ADDRESS	Read Only

5. Operator Level 2

Level 2 provides access to additional parameters. Access to these is protected by a security code.

5.1 To Enter Level 2

- 1. From any display press and hold
- After a few seconds the display will show:-
- 3. Release

(If no button is pressed for about 45 seconds the display returns to the HOME display)

- 4. Press or to choose LEu 2 (Level 2
- 5. After 2 seconds the
- display will show:-
- 6. Press \frown or \bigtriangledown to enter the pass code. = (10) 1,
- If an incorrect code is entered the controller reverts to Level 1.

5.2 To Return to Level 1

- 1. Press and hold
- 2. Press A to select LEu 1

The controller will return to the level 1 HOME display. Note: A security code is not required when going from a higher level to a lower level.

5.3 Level 2 Parameters

Press to step through the list of parameters. The mnemonic of the parameter is shown in the lower display. After five seconds a scrolling text description of the parameter appears.

The value of the parameter is shown in the upper display. Press or to adjust this value. If no key is pressed for 30 seconds the controller returns to the HOME display

Backscroll is achieved when you are in this list by pressing while holding down .

The following table shows a list of parameters available in Level 2.

6. Access to Further Parameters

Parameters are available under different levels of security and are defined as Level 1 (Lev1), Level 2 (Lev2), Level 3 (Lev 3) and Configuration (Conf).

Level 1 has no passcode since it contains a minimal set of parameters generally sufficient to run the process on a daily basis.

Level 2 allows access to parameters which may used in commissioning a controller or settings between different products or batches.

Level 1 and Level 2 operation has been described in the previous sections.

Level 3 and Configuration level parameters are also available as follows:-

6.1.1 Level 3

Level 3 makes all operating parameters available and alterable (if not read only). It is typically used when commissioning a controller.

Examples of parameters available in Level 3 are:-

Range limits, setting alarm levels, communications address.

The instrument will continue to control when in Levels 1, 2 or 3.

6.1.2 Configuration Level

This level makes available all parameters including the operation parameters so that there is no need to switch between configuration and operation levels during commissioning. It is designed for those who may wish to change the fundamental characteristics of the instrument to match the process.

Examples of parameters available in Configuration level are:-

Input (thermocouple type); Alarm type; Communications type.

WARNING

Configuration level gives access to a wide range of parameters which match the controller to the process. Incorrect configuration could result in damage to the process being controlled and/or personal injury. It is the responsibility of the person commissioning the process to ensure that the configuration is correct.

In configuration level the controller is not controlling the process or providing alarm indication. Do not select configuration level on a live process.

Operating Level	Home List	Full Operator	Configuration	Control
Level 1	✓			Yes
Level 2	✓			Yes
Level 3	~	~		Yes
Conf	✓	✓	\checkmark	No

6.1.3 Selecting Recipes (Configuration Level)

Recipes can be selected from Level 3 or the Configuration Level. After successfully entering the password in either of these levels, the button until RECIP appears in the lower display. Press the button once to enter the RECIPE menu. Press the arrow buttons to select the desired recipe. Press the button to exit the RECIPE menu.

Do T	his	The Display You Should See	Additional Notes
1.	From any display press and hold for more than 5 seconds	To Select Level 3	The display will pass from the current operating level, for example, LEu I to LEu \exists as the button is held down. (If no button is then pressed for about 50 seconds the display returns to the HOME display)
2.	Press or to enter the passcode for Level 3	¦ ¦ CODE	The Level 3 code is 11: If an incorrect code is entered the display reverts to 'got o '. The controller is now in the level 3 will then revert to the HOME display
3.	When the LEUJ GOTO view is shown, as in paragraph 1 above, press to select 'LonF'	To Select Configuration level	Note: must be pressed quickly (within 2 seconds) before the controller requests the code for level 3 (If no button is then pressed for about 50 seconds the display returns to the HOME display)
4.	Press or to enter the passcode for Configuration level	iii code EonF	The configuration code is 111: If an incorrect code is entered the display reverts to 'g o t o '. The controller is now in Configuration level will now show LonF
5.	Press and hold for more than 3 seconds Press to select the required level eg LEV 1	To Return to a Lower Level	The choices are: $LEU \mid Level 1$ $LEU \mid Level 2$ $LEU \mid Level 3$ $E \cap F$ Configuration It is not necessary to enter a code when going from a higher level to a lower level. Alternatively, press and scroll to the Acces list header, then press to select the required level. The display will then flash ' $E \cap F$ ' for a few seconds and the controller will then go through its start up sequence, starting in the level selected. Do not power down while $E \cap F$ is flashing. If a power down does occur an error message will appear.
			Do not power down while LonF is flashing. If a power down does occur an error message will appear.

6.1.4 To Select Access Level 3 or Configuration Level

☑ A special case exists if a security code has been configured as '0' If this has been done it is not necessary to enter a code and the controller will enter the chosen level immediately.

When the controller is in configuration level the ACCESS list header can be selected from any view by holding down the button for more than 3 seconds.
 Then press again to select 'ACCES'

6.2 Parameter lists

Parameters are organised in lists. The top of the list shows the list header only. The name of the list header describes the generic function of the parameters within the list. For example, the list header 'ALARM' contains parameters which enable you to set up alarm conditions.

6.2.1 To Choose Parameter List Headers

Press _____. Each list header is selected in turn every time this key is pressed.

The name of the list header appears in the lower display, followed, after a few seconds, by a scrolling longer description of the name.

The following example shows how to select the first two list headers. (Views are shown for 3216 controllers).



6.2.2 To Locate a Parameter

Choose the appropriate list, then press . Each parameter in the list is selected in turn each time this button is pressed. The following example shows how to select the first two parameters in the ALARM List. All parameters in all lists follow the same procedure. (Views are shown for 3216 controllers).



6.2.3 How Parameters are Displayed

As shown above, whenever a parameter is selected it is displayed as a mnemonic, of four or five characters, for example 'A1.TYP'.

After a few seconds this display is replaced by a scrolling banner which gives a more detailed description of the parameter. In this example 'A1.TYP' = 'alarm 1 type'. The scrolling banner is only shown once after the parameter is first accessed. (Views are shown for 3216 controllers).



The name of the list header is also displayed in this way.

The upper part of the display shows the value of the parameter.

The lower part shows its mnemonic followed by the scrolling name of the

parameter

6.2.4 To Change a Parameter Value

With the parameter selected, press to increase the value, press to decrease the value. If either key is held down the analogue value changes at an increasing rate.

The new value is entered after the key is released and is indicated by the display blinking. The exception to this is output 'Power' when in manual. In this case the value is entered continuously.

The upper display shows the parameter value the lower display shows the parameter name.

6.2.5 To Return to the HOME Display Press + .

On release of the keys the display returns to the HOME list. The current operating level remains unchanged.

6.2.6 Time Out

A time out applies to the 'Go To' and 'Control Mode' parameters. If no key presses are detected within a period of 5 seconds the display will revert back to the HOME list.



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6.3 Navigation Diagram

The diagram below shows the all list headings available in configuration level for 3216 controllers.

The parameters in a list are shown in tables in the following sections of this manual together with explanations of their meanings and possible use.



7. Custom Scrolling Text

The 3216 has custom scrolling text used to provide detailed information about the status of the process. The scrolling text will appear in the lower readout of the display. The following is a list of custom scrolling text messages used.

Controller	Scrolling Display	Description
Water Unit (TCU)	VENTING IN PROCESS	On power up, the vent valve opens for 60 seconds to allow air to bleed out of the system. This text displays for the 60seconds.
1 Compressor Chiller	COMPRESSOR ON	This text displays when the compressor turns on. It will remain on until the compressor turns off.
1 Compressor Chiller	COMPRESSOR OFF	This text displays when the compressor turns off. It will remain on until the compressor turns on.
2 Compressor Chiller	COMPRESSOR A ON COMPRESSOR B ON	This text displays when either or both compressors are on. It will remain on until either or both compressors turn off.

Custom Configurations

See Appendix B for tables summarizing the parameter values for each of the custom configurations.

7.1.1 Master Parameter List

INPUT LIST I NPUT							
Name	Scrolling Display	Parameter Description	Value	Value		Access Level	
IN.TYP	INPUT TYPE	Selects input linearisation and range	See manu	facture manual for input types available		Conf L3 R/O	
UNITS	DISPLAY UNITS	Display units shown on the	попЕ	No units - only for custom linearisation	۰Ľ	L3	
		instrument	۰Ľ	Celsius			
			۰F	Fahrenheit			
			∘⊩	Kelvin			
			PErc	%			
DEC.P	DISPLAY	Decimal point position	лллл	No DP	пппп	Conf	
	POINTS		пппл	One DP		L3 R/O	
			חת.חח	Two DP			
MV.HI	LINEAR INPUT HIGH	High limit for mV (mA) inputs	-10.00 to	+80.00mV	80.00	Conf	
MV.Lo	LINEAR INPUT LOW	Low limit for mV (mA) inputs	-10.00 to	-10.00 to +80.00mV		Conf	
RNG.HI	RANGE HIGH	Range high limit for thermocouple	From the	From the high limit of the selected input type to the		Conf	
	LIMIT	RTD and mV inputs	'Low Ran	'Low Range Limit' parameter minus one display unit.		L3 R/O	
RNG.LO	RANGE LOW	Range low limit for thermocouple	From the	From the low limit of the selected input type to the		Conf	
	LIMIT	RTD and mV inputs	High Rai	nge Limit' parameter minus one display unit.		L3 R/O	
PV.OFS	PV OFFSET	A simple offset applied to all input values.	Generally	one decimal point more than PV		L3	
FILT.T	FILTER TIME	Input filter time	OFF to 10	00.0 seconds	1.6	L3	
CJ.typ	CJC TYPE	Configuration of the CJC type	Auto	Automatic	Ruto	Conf and if	
			0•C	Fixed at 0°C	1	T/C	
			50°C	Fixed at 50°C	1	L3 R/O	
SB.typ	SENSOR BREAK	Defines the action which is applied	oFF	No sensor break will be detected	п	Conf	
	TYPE	to the control output if the sensor	п	Open circuit sensor will be detected	_	L3 R/O	
		breaks (open circuit).	LAF	Latching	1		
CJC.in	CJC	Temperature measured at the rear	Read only	7		Conf	
	TEMPERATURE	terminal block. Used in the CJC calculation				L3 R/O and if T/C	
Pv.in	PV INPUT	Current measured temperature	Minimum	display to maximum display range		Conf	
	VALUE					L3 R/O	
mv.in	MILLIVOLT	Millivolts measured at the rear PV	xx.xx mV	- read only		Conf	
	INPUT VALUE	Input terminals				L3 R/O	

INPUT/OUT	INPUT/OUTPUT LIST 1 4 O -1 '							
Name	Scrolling Display	Parameter Description		Value	Default	Access Level		
1i d	i d I/O 1 TYPE I/O channel 1 hardware typ defined by the hardware fitted	I/O channel 1 hardware type	nonE	No input or output fitted	As	Read only		
		fitted	dC.0P	DC output	ordered			
			ГЕГА	Relay output				
		LJO	Logic Input/Output					
			557	Triac output				
1.FUNC	I/O 1 FUNCTION	FUNCTION I/O channel function.	nonE	Disabled. If disabled no further parameters are shown	HERE	Conf		
		as valve positioner (codes	d.out	Digital output				
	VC ava d.c	VC or VP), only options available are, nonE, dout, UP, or dwn	UР	Valve open codes VC and VP only	_			
			dwn	Valve close codes VC and VP only				
			HEAF	Heat output				
		Note: If output 1 is set to	Eool	Cool output				
UP ensure the other valve	пıр	Digital input if '1.i d ' = 'LJ 🛙						
	position output is set to	w.SP	Working setpoint re-transmission	Shown if	I/O 1 TYPE =			
		and vice versa	PU	Process variable re-transmission	dc.DP Retransmission	transmission		
			OP	Output power demand re-transmission				

INPUT/OUTPUT LIST 1 'I O -1 '						
Name	Scrolling Display	Parameter Description		Value	Default	Access Level
1.SRC.A	I/O 1 SOURCE A	These parameters only	NonE	No event connected to the output	попЕ	Conf
1.SRC.B	I/O 1 SOURCE B	appear when the channel	AL I	Alarm 1		
		function is a Digital output,	AL2	Alarm 2		
1.SRC.C	I/O 1 SOURCE C	i.e. 1.FUNC = d.out	ALB	Alarm 3	-	
		Selects an event status to be	ALY	Alarm4		
1.SRC.D	I/O 1 SOURCE D	connected to the output	ALL A	All alarms		
		channel.	nw.AL	Any new alarm		
		The output status is the	EFar	CT alarm, load, leak & overcurrent		
		result of an OR of Src A	Lbr	Loop break alarm		
		Src B, Src C, and Src D	Sbr	Sensor break alarm		
			E.End	Timer end status		
		Up to four events can,	Erun	Timer run status		
		therefore, operate the output	Au	Manual status		
			rm£.F	Remote fail	_	
			Purf	Power fail	_	
			PrGE	Programmer event.		
1.D.IN	DIGITAL INPUT	This parameter is only	Hont	Input not used	HCHL	Conf
	FUNCTION	applicable to I/O I and only appears if the channel	Ac.AL	Alarm acknowledge		
		function is a Digital IP	SP2	Setpoint 2 select		
		i.e. 1.FUNC = d, n	Loc.b	Front keypad disable (keylock)		
		Only one function may be	FrE2	Timer/programmer reset		
		activated by a physical input	Erun	Timer/programmer run		
			£.r.5	Timer/programmer run/reset. Make to run, break to reset		
			FHL9	Timer/programmer hold	-	
			mAn	Manual status	-	
			569	Standby mode. In this mode control	-	
			Г -L	Demote disitel extension enland	-	
				Remote digital setpoint select	-	
				Recipe select through IOI digital input	-	
				Remote key Up	-	
				Remote key 'Down'		
1.PLS	OUTPUT 1 MINIMUM DUI SE	Minimum output on/off	UU to	Auto or 1.0 to 150.0 seconds	5.0 sec	Conf
	TIME	Only applies to time	ט.טבי	Auto = 110mS	relay.	
		proportioning outputs and			Auto for	
		prevents relays from			logic	
		switching too rapidly				
1.SENS	I/O 1 SENSE	To configure the sense of	חפר	Normal	חםר	Conf
		the input or output channel	lnu	Inverted		
1.rng	DC OUTPUT	To configure 0-20mA or 4-	0.20	0-20mA output	_	L3
	RANGE	20mA output	4.20	4-20mA output		
		Only appears if the output module is DC output				

OUTPUT LIST 2 'op-2'									
Name	Scrolling Display	Parameter Description		Value	Default	Access Level			
2.i d	OUTPUT 2	Output channel 2 hardware	попЕ	Output not fitted	As ordered	Read only			
TIFE	THE	type	гЕНЧ	Relay output					
			LDP	Logic output (3200 only)					
			dC.DP	0-20mA output.					
		556	Triac output						
2.FUNC	FUNCTION	Output channel 2 function If the instrument is ordered as	NonE	Disabled. If disabled no further parameters are shown	d.out	Conf			
		valve positioner (codes VC or	d.out	Digital output	1				
		VP), only options available are	UР	Valve open codes VC and VP only]				
		, nont, d.out, UP, or	dwn	Valve close codes VC and VP only					
		השם	HERE	Heat output					
		Note: If output 2 is set to UP	Eool	Cool output					
		ensure the other valve	w.SP	Working setpoint re-transmission	Shown if I/C	2 TYPE =			
	position output is set to dun		PU	Process variable re-transmission	dc.0P Retra	nsmission			

		and vice versa	0P	Output power demand re-transmission		
2.SRC.A	I/O 2 SOURCE	These parameters only appear	nonE	No event connected to the output	nonE	Conf
	A	when the channel function is a	AL I	Alarm 1 *		
2.SRC.B	C.B $I/O 2 SOURCE$ B $i.e. 2.FUNC = d \squareut$		AL2	Alarm 2 *		
		AL 3	Alarm 3 *	_		
2.SRC.C	I/O 2 SOURCE	Selects an event status to be	ALY	Alarm4 *		
	C	connected to the output	ALLA	All alarms		
2.SRC.D	I/O 2 SOURCE	channel.	nw.AL	Any new alarm		
	D	The output status is the result	EFar	CT alarm, load, leak & overcurrent		
		of an OR of Src A, Src B, Src	Lbr	Loop break alarm		
		C, and Src D	Sbr	Sensor break alarm		
		Up to four events can,	L.End	Timer end status		
	therefore, operate the ou	therefore, operate the output	Erun	Timer run status	-	
			mAn	Manual status		
			rmbF	Remote fail		
			Pur F	Power fail		
			PrG.E	Programmer event.		
2.PLS	OUTPUT MINIMUM PULSE TIME	Minimum output on/off time. Only applies to time proportioning outputs and prevents relays from switching too rapidly	0.0 to 150.0	Auto or 1.0 to 150.0 seconds Auto = 110mS	5.0 sec for relay Auto for logic	Conf
2.SENS	SENSE	To configure the polarity of	пог	Normal	пог	Conf
		output channel 2	lnu	Inverted		
2.rng	DC OUTPUT	To configure 0-20mA or 4-	0.20	0-20mA output	_	L3
	KANGE	Only appears if the output module is DC output	4.20	4-20mA output		

AA RELAY 'aa'								
Name	Scrolling Display	Parameter Description		Value	Default	Access Level		
4.TYPE	OUTPUT 4 TYPE	Output channel 4 hardware type	гELЫ	Relay output	гЕГА	Read only		
4.FUNC	FUNCTION	Output channel 4 function	попЕ	Disabled	d.DUE	Conf		
	If the instrument is ordered as valve positioner (codes VC or VP) only options available ar	d.DUL	Digital output					
		VP) only options available are	UР	Valve open codes VC and VP only				
		, nonE, dout, UP, or	dwn	Valve close codes VC and VP only				
	dwn	HERE	Heat output					
		Note: If output 4 is set to uP ensure the other valve position output is set to dun and vice versa	Cool	Cool output				
4.SRC.A	I/O 4 SOURCE	YO 4 SOURCE These parameters only appear when the channel function is a Digital OP, i.e. 4.FUNC = dilut	попЕ	No event connected to the output	попЕ	Conf		
	Α		AL I	Alarm 1 *				
4.SRC.B	I/O 4 SOURCE		AL2	Alarm 2 *				
	В		AL 3	Alarm 3 *				
4.SRC.C	I/O 4 SOURCE	Selects an event status to be	ALY	Alarm4 *				
	С	connected to the output	ALLA	All alarms				
4.SRC.D	I/O 4 SOURCE		nu.AL	Any new alarm				
	D	The output status is the result of an OR of Src A, Src B, Src C, and Src D	EFAT	CT alarm, load, leak & overcurrent				
			Цыг	Loop break alarm	_			
			Sbr	Sensor break alarm	_			
		Up to four events can,	E.End	Timer end status	_			
		therefore, operate the output	Erun	Timer run status	_			
			mHn	Manual status	_			
			rmbF	Remote fail	_			
			Purt	Power fail	_			
			PrGE	Programmer event.				
4.PLS	OUTPUT MINIMUM PULSE TIME	Minimum output on/off time. Only applies to time proportioning outputs and prevents relays from switching too rapidly	150.0	0 to 150 seconds	5.0 sec	Conf		

I	4.SENS	SENSE	To configure the polarity of	пог	Normal	пог	Conf
			output channel 4	lnu	Inverted		

LOGIC INPUT LIST 'la'/'LB'									
Name	Scrolling Display	Parameter Description		Value	Default	Access Level			
L.TYPE	LOGIC INPUT TYPE	Input channel type	LJP	Logic input	As order code	Conf Read only			
L.d.in	LOGIC INPUT	To configure the function of the	nonE	Input not used	Ac AL	Conf			
	FUNCTION	digital input	Ac.AL	Alarm acknowledge					
			SP2	Setpoint 2 select	_				
			Loc.b	Front keypad disable					
			FrE2	Timer/programmer reset					
			Erun	Timer/programmer run					
			Err5	Timer/programmer run/reset. Make to run, break to reset					
			FHT	Timer/programmer hold					
			mAn	Manual status					
			569	Standby mode. In this mode control outputs go to zero demand					
			rmt	To allow a remote setpoint to be selected through the LA digital input.					
			rEc	Recipe select through IO1 digital input					
			UР	Remote key 'Up'					
			dwn	Remote key 'Down'					
L.SENS	LOGIC INPUT	To configure the polarity of the	пог	Normal	пог	Conf			
SENSE	SENSE	input channel	l nu	Inverted	1				
			4.20	4-20mA output]				

SETPOINT L	IST 'SP'					
Name	Scrolling Display	Parameter Description	Value		Default	Access Level
SP.SEL	SETPOINT	This enables the main or secondary	SP I	SP Setpoint 1 selected		L3
	SELECT	setpoint to be selected form the front panel buttons	SP2	Setpoint 2 selected	-	
S P 1	SETPOINT 1	Main or normally selected setpoint	Low to his	gh setpoint limits	0	L3
SP2	SETPOINT 2	Secondary or standby setpoint	Low to his	gh setpoint limits	0	L3
SP.HI	SETPOINT HIGH LIMIT	Maximum allowable setpoint setting	Setpoint le limit. Als RNG.L0 pa	ow limit (SP.LO) to high range o limited by the RN5.HI and rameters	Range High Limit	L3
SP.LO	SETPOINT LOW LIMIT	Minimum allowable setpoint setting	Low range limit to Setpoint high limit (SP.HI). Also limited by the RN5.HI and RN5.LD parameters		Range Low Limit	L3
r Em.sp	REMOTE SETPOINT	Reads the current remote setpoint value when remote setpoint is in use				Read only
l - r	REMOTE To select the remote digital		Πο	Not selected	по	Conf
	SELECT	communications setpoint	YE5 Selected			
SP.RAT	SETPOINT RATE	Limits the rate of change of the setpoint.	Step chan	ge (OFF) or D. I to 3000	OFF	L3
		Operates on bour SF1 and SF2	Resolution	ns per minute.		
			PV			
rampu	SETPOINT RAMP	To set the units for the setpoint rate limit	шц	Minutes	mi n	L3
	UNITS		Ноог	Hours		
			SEC	Seconds		
loc.t	LOCAL SETPOINT TRIM	To apply a fixed offset to the setpoint in use	-199.9 to 300.0		0.0	L3
REM.HI	REMOTE INPUT HIGH SCALAR	Sets the maximum scale limit for the remote setpoint	Between Range High and Low Limits			L3
REM.lo	REMOTE INPUT LOW SCALAR	Seta the minimum scale limit for the remote setpoint				

CONTROL LIST	'CTRL'				
Parameter	Parameter Description	Value		Default	Access
Name	(Scrolling Display)				Level
CTRL.H	HEATING TYPE	Pid	PID	As order	Conf
	Selects the channel 1 control algorithm.	۵FF	Heating off	code	
	Different algorithms may be selected for	on.oF	On/Off	-	
	applications, Ch1 is usually the heating channel, Ch2 is the cooling channel.	mEr	Valve position control	-	
CTRL.C	COOLING TYPE	۵FF	Cooling disable	As order	Conf
	Selects the channel 2 Control algorithm.	Pid	PID	code	
	Different algorithms may be selected for channels 1 and 2.		On/Off		
	This is not available if the instrument is a valve position controller				
CTRL.A	CONTROL ACTION Selects the direction of the control. i.e reverse	Reverse acting. Output decreases as PV increases		rtu	Conf
	or direct acting.	dir	Direct acting. Output increases as PV decreases		
PB.UNT	PROPORTIONAL BAND UNITS	EnG	In engineering units		
		PErc	In percent		
ATUNE	AUTO-TUNE ENABLE	DFF	Autotune off	DFF	L3
		On	Set to 'on' to start auto-tuning		
PB	PROPORTIONAL BAND	0.1 t 9999 display units or 1 to 999 9% if proportional band expressed as %		20	L3
ТІ	INTEGRAL TIME	IFF to 9999 seconds		∃БЛ sec	L3
TD	DERIVATIVE TIME	TFF to 9999 seconds		БП sec	L3
		TD defaults to DFF for valve position control			20
R2G	RELATIVE COOL GAIN	0.1 to 10.0		1.0	L3
СВНі	CUTBACK HIGH	RuEo or 1 to 3000 display units		Auto = 3xPb	L3
CBLo	CUTBACK LOW	Auto or 1 to 3000 display units		Hulo = 3XPb	L3
MR	MANUAL RESET	0.0 to 100.0	% (heat only) 0 0% (heat/cool)	0.0%	L3
IBT	LOOP BREAK TIME	ΠFF	Setting loop Break Time to OFF disables	NFF	L3
	The loop break alarm attempts to detect loss of restoring action in the control loop by checking the control output, the process value and its rate of change.	1 to 9999 m	the Loop Break Alarm	_	
	Loop break detection works for all control algorithms: PID, VP and ON-OFF.				
	Note: This is not to be confused with load failure and partial load failure.				
OP.HI	OUTPUT HIGH	<u>+</u> 100.0%		100.0%	L3
	Adjust to limit the maximum heating power applied to the process				
OP.LO	OUTPUT LOW	<u>+</u> 100.0%		0.0 (heat	L3
	Adjust to limit the maximum cooling power applied to the process or to apply a minimum heating power			only) -100 (cool)	
MTR.T	MOTOR TRAVEL TIME	0.0 to 999.	9 seconds	0.0	L3
	Set this value to the time that it takes for the motor to travel from its fully closed to its fully open position.	Note: In mo parameters a the control.	otorised valve control only the PB and TI are active. The TD parameter has no effect on		
D.BAND	CHANNEL 2 DEAD BAND		to 100.0% of the cooling proportional hand	OFF	L3
	Period when no output is demanded from either channel 1 or channel 2 Adjust, for example, to increase the period		ð I - I		
HYST H	HEATING HYSTERESIS	_199.0 to 20	10.0 display units	1	I 3 On/off
HYST.C	COOLING HYSTERESIS	-199.9 to 20	0.0 display units	1	only

				1	
SAFE	SAFE OUTPUT POWER	-100.0 to	100.0% limited by OP.HI and OP.LO	0.0%	L3
	To set the output level in a sensor break (open circuit) condition				
F.MOD	F.MOD FORCED MANUAL OUTPUT MODE Selects how the loop behaves on transfer from		Transfer between Auto/Manual/Auto is bumpless	попЕ	L3
Auto to Man Transfer from bumpless.	Auto to Manual. Transfer from Manual to Auto is always bumpless.	SEEP	Transfer from Auto to Manual, the output goes to a pre-set value (F.OP)		
		LASE	Transfer from Auto to Manual, the output goes to the previously set manual value	_	
Cool.t	NON-LINEAR COOLING TYPE	Lin	Linear	As order	Conf
T ty	This selects an algorithm most suited to the type of cooling. Typically used in extruders.	DI L	Oil cooling	code	
		H50	Water cooling		
		FAn	Forced air cooling		
F.OP	FORCED OUTPUT	-100.0 to	100.0% limited by OP.HI and OP.LO	0.0	L3
	To pre-set a value for the Manual output when F.MOD = STEP				
A-M	LOOP MODE - AUTO MANUAL OFF	Ruto	To select automatic operation		L3
		mAn	To select manual operation		
		DFF	Control outputs inhibited]	
lbr	LOOP BREAK STATUS	П <u>ь</u> 465	Shows the current status of loop break.		Read only

ALARM LI	ST 'ALARM'					
Name	Scrolling Display	Parameter Description	Value		Default	Access Level
A1.TYP	ALARM 1 TYPE	Selects the type of alarm	nonE	Alarm not configured	As order	Conf
			Hi	Full Scale High	code	
			Lo	Full Scale Low		
			ĿНı	Deviation High		
			d.Lo	Deviation Low		
			bnd	Deviation band		
A1	ALARM 1 SETPOINT	Alarm 1 threshold value.	Instrument range		0	L3
		The last three characters show the type of alarm configured from the above list				
A1.sts	ALARM 1 OUTPUT	Indicates the status of the alarm	DFF	Alarm off		Read only
			On	Alarm on		
A1.HYS	ALARM 1 HYSTERESIS	See description in manufacture manual	0 to 9999			Conf
A1.LAT	ALARM 1	See description in manufacture manual	nonE	Non-latching	As order	Conf
	LATCHING TYPE		Auto	Latching with automatic resetting	code	
			mAn	Latching with manual resetting		
			Eut	Event (no alarm flashing beacon but messages can be displayed)		
A1.BLK	ALARM 1	See description in manufacture manual	Πο	No blocking	Πο	Conf
	BLOCKING		YE5	Blocking	7	
The above pa	arameters are repeated for A	larm 2, A2; Alarm 3, A3; Alarm 4, A4				

TIMER LIST	"timer"	timer"							
Name	Scrolling Display	Parameter Description	Value			Default	Access Level		
TM.CFG	TIMER CONFIGURAT ION Timer type configuration dwEll dELY	Timer disabled		As order	L3				
			dwEll	Dwell	code	code			
			dELY	Delayed switch on					
			SFSE	Soft start					
			ProG	Programmer					
TM.res	TIMER RESOLUTION	IER To set the time units OCLUTION	Ноиг	Hours	HH:MM		Conf R/O L3		
			min	Minutes	MM:SS	1			

TIMER LIST	"timer"					
Name	Scrolling Display	Parameter Description	Value		Default	Access Level
THRES	TIMER START THRESHOLD	To set the maximum deviation between SP and PV before the timer starts.	OFF or 1 t	to 3000 Units above and below setpoint	OFF	L3
		Dwell timer and Programmer only				
ENd.T	TIMER END	To determine the action which	DFF	Control outputs go to zero %		Conf
	TYPE	takes place when the timer has timed out.	dwEll	Control continues at SP1		
		Dwell timer and	SP2	Go to setpoint 2	_	
		Programmer only	rt5	Reset programmer		
SS.SP	SOFT START SETOINT	Sets the threshold below which the power is limited 5F5L timer only	Controller i	nput range	0	Conf
SS.PWR	SOFT START POWER LIMIT	Sets the limit to the power output during start up SFSL timer only	0 to 100%		0	Conf
T.STAT	TIMER	Timer status	rE5	Reset		L3
	STATUS		гип	Running (counting)		
			hold	Running (hold)		
			End	Timed out		
Servo		Defines the way in which the programmer starts and how it recovers from a power failure	SP	Starts at SP1 (or SP2). The program must be re-started after a power failure.	SP	
		Programmer only	PII	Starts at the current Process value.	-	
				The program must be re-started after a power failure.		
			SP, ь	Starts at SP1 (or SP2).		
				The program will continue to run from the original setpoint value at the last ramp rate.		
			Риль	Starts at the current Process value.		
				The program will continue to run from the current process value and ramp back at the last ramp rate		
Tsp.1	TARGET SETPOINT 1	To set the target value for the first setpoint	Controller i	nput range	0	L2
R m p . 1	RAMP RATE 1	To set the rate at which the setpoint changes to reach TSP.1	DFF , 0:1 to	o 3000 units per min or hour	DFF	L2
Dwel.1	DWELL 1	To set the time at which the setpoint remains at TSP.1	DFF , 0:01	to 99:59 hh:mm or mm.ss	DFF	L2
The above thre	e parameters are rep	eated for the next 3 program segme	nts, i.e. TSP.2	, (3 & 4), RMP.2 (3 & 4), DWEL.2 (3 & 4)	1	
dwell	SET TIMER DURATION	To set the time duration (not programmer)	0:00 to 99:5	59 hh:mm or mm.ss	0	L3
T.ELAP	ELAPSED TIME	Time elapsed from when the timer starts to run	0:00 to 99.5	59 hh:mm or mm.ss		L3 read only
T.REMN	TIME REMAINING	Time remaining to reach the set time.	0:00 to 99.5	59 hh:mm or mm.ss		L3
event	EVENT OUTPUTS	Event output operates during the selected segment Programmer only	0 = No even 255 -= Even	nts operate in any segment nts operate in all segments	0	L3
p.cycl	PROGRAM CYCLES	Sets the number of times that a program is repeated	1 to 100		1	L3
cycle	PROGRAM CYCLE	Displays the current cycle when the program is running	1 to 100			L3
The timer can l						

CALIBRATION PARAMETER LIST

'cAL'

Name	Scrolling Display	Parameter Description	Value		Default	Access Level
ucal	USER	To select low and high	I dLE	Normal operating state	I dLE	L3 only
	CALIBRATION	offset state or reset to no	Lo	Low offset		
		onsets.	H,	High offset		
			rESE	Remove high and low offsets		
The follow	ing parameters appear v	when calibrating the controller	ie UCAL = L	o or Hi		
c.adj	CALIBRATION ADJUST	To set an offset value.	-1999 to 9	999		L3 only
phase	CAL PHASE	To calibrate low and high	попЕ	Not selected	nonE	Conf only
		offset	۵	Select mV low calibration point		
			50	Select mV high calibration point		
			150r	Select PRT low cal point		
			400r	Select PRT high cal point		
			IL 3	Select CJC calibration		
			EF D	Select CT low cal point		
			CF 70	Select CT high cal point		
			FAct	Return to factory settings		
			ImAL	Low mA output from I/O 1		
			¦mAH	High mA output from I/O 1		
			2mAlL	Low mA output from output 2		
			5™B`H	High mA output from output 2		
			3mAL	Low mA output from output 3		
			∃mRH	High mA output from output 3		
			rm.UL	Remote setpoint input low volts		
			┍╖╝╫	Remote setpoint input high volts		
			rm.EL	Remote setpoint input low current		
			г <i>т.</i> ЕН	Remote setpoint input high current		
GO		To start the calibration	ПО		ПО	Conf only
		sequence	YES	Start		
			6059	Calibrating		
		-	PASS	Calibration successful		
			FRiL	Calibration unsuccessful		

8. Diagnostic Alarms

Diagnostic alarms indicate a possible fault within the controller or connected devices.

Display shows	What it means	What to do about it	
E£onF	A change made to a parameter takes a finite time to be entered. If the power to the controller is turned off before the change has been entered then this alarm will occur. Do not turn the power off to the controller while LonF is flashing	Enter configuration mode then return to the required operating mode. It may be necessary to re-enter the parameter change since it will not have been entered in the previous configuration.	
E.E.AL	Calibration error	Re-instate Factory calibration	
E2.Er	EEPROM error	Return to factory for repair	
EE.Er	Non-vol memory error	Note the error and contact your supplier	
ELin	Invalid input type. This refers to custom linearisation which may not have been applied correctly or may have been corrupted.	Go to the INPUT list in configuration level and set a valid thermocouple or input type	
Emod	IO1, OP2, or OP3 has been changed	If this has been field changed by the installation of a new board, enter config level, then exit back to operator level. If the message occurs at any other time return to factory	
		for repair.	

8.1.1 Out of Range Indication

If the input is too high HHHHH will be displayed If the input is too low LLLLL will be displayed

9. Digital Communications

Digital Communications (or 'comms' for short) allows the controller to communicate with a PC or a networked computer system. Digital communications is not available in 3116 controllers.

This product conforms to MODBUS RTU [®] protocol a full description of which can be found on www.modbus.org.

Two ports are available both using MODBUS RTU communication facilities:

- 1. a configuration port intended to communicate with a system to download the instrument parameters and to perform manufacturing tests and calibration
- 2. an optional RS232 or RS485 port on terminals HD, HE and HF intended for field communications using, for example, a PC running a SCADA package.

The two interfaces cannot operate at the same time.

For a full description of digital communications protocols (ModBus RTU) refer to the 2000 series Communications Handbook, part number HA026230, available on <u>www.eurotherm.co.uk</u>.

Each parameter has its own unique ModBus address. A list of these is given at the end of this section.

9.1 Digital Communications Wiring

9.1.1 RS232

To use RS232 the PC will be equipped with an RS232 port, usually referred to as COM 1.

To construct a cable for RS232 operation use a three core screened cable.

The terminals used for RS232 digital communications are listed in the table below. Some PC's use a 25 way connector although the 9 way is more common.

Standard Cable	PC socke no.	et pin	PC Function *	Instrument Terminal	Instrument
Colour	9 way	25 way			Function
White	2	3	Receive, RX	HF	Transmit, TX
Black	3	2	Transmit, TX	HE	Receive, RX
Red	5	7	Common	HD	Common
Link together	1	6	Rec'd line sig.		
	4	8	detect Data terminal ready		
	6	11	Data set ready		
Link	7	4	Request to		
logeniei	8	5	Clear to send		
Screen		1	Ground		

* These are the functions normally assigned to socket pins. Please check your PC manual to confirm.

9.1.2 RS485 (2-wire)

To use RS485, buffer the RS232 port of the PC with a suitable RS232/RS485 converter. The Eurotherm Controls KD485 Communications Adapter unit is recommended for this purpose. The use of a RS485 board built into the computer is not recommended since this board may not be isolated, which may cause noise problems, and the RX terminals may not be biased correctly for this application.

To construct a cable for RS485 operation use a screened cable with one (RS485) twisted pair plus a separate core for common. Although common or screen connections are not necessary, their use will significantly improve noise immunity.

The terminals used for RS485 digital communications are listed in the table below.

Standard Cable Colour	PC Function *	Instrument Terminal	Instrument Function
White	Receive, RX+	HF (B) or (B+)	Transmit, TX
Red	Transmit, TX+	HE (A) or (A+)	Receive, RX
Green	Common	HD	Common
Screen	Ground		

• These are the functions normally assigned to socket pins. Please check your PC manual to confirm .

See section 2.12 for wiring diagrams

9.2 Digital Communications Parameters

The following table shows the parameters available.

DIGITAL COMMUNICATIONS LIST 'comms'						
Name	Scrolling Display	Parameter Description	Value		Default	Access Level
I D	MODULE	Comms identity	попЕ	No module fitted	As order	Conf
	IDENTITY		r232	RS 232 Modbus interface	code	L3 R/O
			r485	RS485 Modbus interface	-	
			r422	RS422 Modbus 3216 only	-	
			dc, Р	Remote setpoint input. If fitted this ID replaces the above and no further parameters are shown		
ADDR	COMMUNIC ATIONS ADDRESS	Communications address of the instrument	1 to 29	54	1	L3
BAUD	COMMUNIC	Communications baud rate	1200	1200	9600	Conf
	ATIONS BAUD RATE		2400	2400		L3 R/O
			4800	4800		
			9600	9600		
			19.20	19,200		
PRTY	COMMUNIC	Communications parity	попЕ	No parity	попЕ	Conf
	ATIONS PARITY		EuEn	Even parity		L3 R/O
			Odd	Odd parity		
DELAY	RX/TX	To insert a delay between	DFF	No delay		Conf
	TIME	Rx and Tx to ensure that drivers have sufficient time to switch over.	חם	Fixed delay applied		L3 R/O
Retran	COMMS	Master comms broadcast	попЕ	None	nonE	
	RETRANSM	parameter.	w.5P	Working setpoint		
			PU	Process Variable		
			DP	Output demand	_	
			Err	Error		
reg.ad	COMMS RETRANSM ISSION ADDRESS	Parameter added in the Slave address to which the master communications value will be written	0 to 99	99		

D	Demmed N	M. Jh., 11
Parameter Mnemonic	Parameter Name	Modbus Address
PV.IN	PV (Temperature) Input Value (see also Modbus address 203 which allows writes over Modbus to this variable).	1
TG.SP	Target Setpoint.	2
	NB – do not write continuously changing values to this variable. The memory technology used in this product has a limited (100,000) number of write cycles. If ramped setpoints are required, consider using the internal ramp rate function or the remote comms setpoint (Modbus address 26)in preference.	
MAN.OP	Manual Output Value	3
WRK.OP	Working Output	4
WKG.SP	Working Setpoint (Read Only)	5
РВ	Proportional Band	6
Ti	Integral Time (0 = No Integral Action)	8
Td	Derivative Time	9
A1	Alarm 1 Threshold	13
A2	Alarm 2 Threshold	14
T.STAT	Timer Status	23
	0 = Reset	
	1 = Run	
	2 = Hold	
SP1	3 = End Setpoint 1	24
511	NB – do not write continuously changing values to this variable. The memory technology used in this product has a limited (100,000) number of write cycles. If ramped setpoints are required, consider using the internal ramp rate function or the remote comms setpoint (Modbus address 26) in preference.	24
SP2	Setpoint 2	25
	NB – do not write continuously changing values to this variable. The memory technology used in this product has a limited (100,000) number of write cycles. If ramped setpoints are required, consider using the internal ramp rate function or the remote comms setpoint (Modbus address 26)in preference.	
OP.HI	Output High Limit	30
OP.LO	Output Low Limit	31
SP.RAT	Setpoint Rate Limit Value (0 = no rate limit)	35
StAt	Instrument Status. This is a bitmap:	75
	B0 – Alarm 1 Status	
	B2 – Alarm 3 Status	
	B3 – Alarm 4 Status	
	B4 – Auto/Manual Status	
	B5 – Sensor Break Status	
	B6 – Loop Break Status	
	B/ – CT High leakage current alarm status	
	B9 – Program End	
	B10 – PV Overrange (by $> 5\%$ of span)	
	B11 – CT Overcurrent alarm status	
	B12 – New Alarm Status	
	B13 – Timer/Ramp Running	
	B14 – Remote (comms) SP Fall B15 – Autotune Status	
	In each case, a setting of 1 signifies 'Active', 0 signifies 'Inactive'.	
43	Alarm 3 Threshold	81
44	Alarm 4 Threshold	82
Home	Home Display.	106
	0 – Standard PV and SP display	
	1 – PV and Output Power display	
	2 – PV and Time remaining display 2 – PV and Timer alonged time display	
	4 – PV and Alarm 1 setpoint	
	5 – PV and Load Current	
	6 – PV only	
	7 – PV and Composite SP/Time remaining	

Parameter Mnemonic	Parameter Name	Modbus Address
	8 – Target setpoint	
	9 – No PV	
	10 - PV is not displayed when controller in Standby	
-	Instrument version number. Should be read as a hexadecimal number, for example a value of 0111 hex is instrument V1.11	107
ADDR	Instrument Comms Address	131

9.4 SPI Parameter Addresses

This instrument variant supports the following SPI Device types (no configuration is required, the devices automatically respond to requests made to these device types).

- Mold Temperature Controller (**DEVID 20**)
- Chiller (**DEVID 21**)
- Dryer (DEVID 22)
- Self Tuning General Purpose Temperature Controller (**DEVID 26**)
- General Purpose Temperature Controls (**DEVID 27**)

NB: The SPI variant of the 3200 controller supports only Fahrenheit units.

The SPI device address is set in the range 32..255 (hexadecimal 20 to FF) using the 'Addr' parameter in the Level 2 scroll list, or in the Level 3 'Comms' List.

9.5 DEVID 20, 21 & 22

Mold Temperature Controllers, Chillers, and Dryer DEVIDs support the following set of parameters.

9.5.1 ЕСНО	
POLL:	20 20
SELECT:	20 21
FORMAT:	Open – 4 Bytes
UNITS:	ASCII
DESCRIPTION:	Controller integrity command. Controller will accept and retain the data provided. The controller will provide the retained data in response to a poll enquiry.
VERSION	
POLL:	20 22
SELECT:	N/A
FORMAT:	Open 4 bytes ASCII
UNITS:	ASCII
DESCRIPTION:	SPI version command. The controller will provide a fixed SPI version number (0400 for 3200).

SETPOINT PROCESS TEMPERATURE

DESCRIPTION:	Temperature at which the process is to be maintained.
UNITS:	٥F
FORMAT:	Numeric
SELECT:	20 31
POLL:	20 30

ALARM, HIGH TEMPERA	TURE DEVIATION
POLL:	20 32
SELECT:	20 33
FORMAT:	Numeric
UNITS:	٥F
DESCRIPTION:	This Value in conjunction with the process setpoint determines at what temperature the high alarm will occur. It must always be positive. NB: in the 3200 this setpoint relates to the <u>first</u> configured alarm in the instrument and is therefore not necessarily a high temperature alarm.

ALARM, HIGH TEMPERATURE DEVIATION POLL: 034 SELECT: 035 FORMAT: Numeric UNITS: °F DESCRIPTION: This Value in conjunction with the process setpoint determines at what temperature the low alarm will occurre instrument and is therefore not necessarily a low temperature alarm.		
POLL:20 34SELECT:20 35FORMAT:NumericUNITS:°FDESCRIPTION:This Value in conjunction with the process setpoint determines at what temperature the low alarm will occur. It must always be positive. NB: in the 3200 this setpoint relates to the second configured alarm in the instrument and is therefore not necessarily a low temperature alarm.	ALARM, HIGH TEMPERAT	FURE DEVIATION
SELECT:20 35FORMAT:NumericUNITS:°FDESCRIPTION:This Value in conjunction with the process setpoint determines at what temperature the low alarm will occurr. It must always be positive. NB: in the 3200 this setpoint relates to the second configured alarm in the instrument and is therefore not necessarily a low temperature alarm.	POLL:	20 34
FORMAT:NumericUNITS:°FDESCRIPTION:This Value in conjunction with the process setpoint determines at what temperature the low alarm will occur. It must always be positive. NB: in the 3200 this setpoint relates to the second configured alarm in the instrument and is therefore not necessarily a low temperature alarm.	SELECT:	20 35
UNITS: °F DESCRIPTION: This Value in conjunction with the process setpoint determines at what temperature the low alarm will occur. It must always be positive. NB: in the 3200 this setpoint relates to the second configured alarm in the instrument and is therefore not necessarily a low temperature alarm.	FORMAT:	Numeric
DESCRIPTION: This Value in conjunction with the process setpoint determines at what temperature the low alarm will occur. It must always be positive. NB: in the 3200 this setpoint relates to the <u>second</u> configured alarm in the instrument and is therefore not necessarily a low temperature alarm.	UNITS:	٥F
	DESCRIPTION:	This Value in conjunction with the process setpoint determines at what temperature the low alarm will occur. It must always be positive. NB: in the 3200 this setpoint relates to the <u>second</u> configured alarm in the instrument and is therefore not necessarily a low temperature alarm.

STATUS PROCESS	
POLL:	
SELECT:	

FORMAT:	16 Bits
UNITS:	None

20 40 N/A

DESCRIPTION:



9.5.2 NG	PROCESSI	
BIT#:		0
DESCRIPTIO	DN:	This status bit states whether this unit is currently processing.
		0 = not currently processing (3200 manual mode)
		1 = processing (3200 auto mode)
ALARM, SYS	STEM	
BIT#:		1
DESCRIPTIO	DN:	This status bit states an alarm is present. In the 3200, this is set if any of the 4 temperature alarms are set, or if Sensor Break, Span Error, or Loop break is set.
ALARM, PR	OCESS	
BIT#		2
DESCRIPTIO	DN:	This bit indicates that an alarm that affects the process has occurred. In the 3200, this is set if any of the 4 alarms are set, or if Sensor Break, Span Error, or Loop break is set.

ALARM, HIGH TEMPERATURE

4

BIT#:

DESCRIPTION:

This status bit states the temperature controller has exceeded its over setpoint deviation. This assumes the 3200 has been set up such that the first configured alarm (e.g. Alarm 2 if Alarm 1 is not configured) is a high alarm.

ALARM, LOW TEMPERATURE

BIT#:	5
DESCRIPTION:	This status bit states the temperature controller has exceeded its below setpoint deviation. This assumes the 3200 has been set up such that the second configured alarm (e.g. Alarm 3 if Alarm 1 is not configured and Alarm 2 is a high alarm) is a low alarm.

STATUS, MACHINE 1

POLL:	20 42
SELECT:	N/A
FORMAT:	16 Bits
UNITS:	None
DESCRIPTION:	Identical to definition of STATUS, PROCESS above

STATUS, MACHINE 2

POLL:	20 44
SELECT:	N/A
FORMAT:	16 Bits
UNITS:	None
DESCRIPTION:	Similar to definition of STATUS, PROCESS above



PROCESSING

BIT#:

0

3200 Series		
DESCRIPTION:	This status bit states whether this unit is currently processing.	
	0 = not currently processing (3200 manual mode)	
	1 = processing (3200 auto mode)	
ALARM, SYSTEM		
BIT#:	1	
DESCRIPTION:	This status bit states an alarm is present. In the 3200, this is set if any of the 4 temperature alarms are set, or if Sensor Break, Span Error, or Loop break is set.	
ALARM, PROCESS		
BIT#	2	
DESCRIPTION:	This bit indicates that an alarm that affects the process has occurred. In the 3200, this is set if any of the 4 alarms are set, or if Sensor Break, Span Error, or Loop break is set.	
ALARM, MACHINE		
BIT#	2	
DESCRIPTION:	This bit indicates that an alarm that affects the machine has occurred. Always set to 0 for 3200.	
FAULT, SENSOR		
BIT#	2	
DESCRIPTION:	This bit indicates a sensor error has been detected. Either sensor break or span error for 3200.	
TEMPERATURE, TO PROC	CESS	
POLL:	20 70	
SELECT:	N/A	
FORMAT:	Numeric	
UNITS:	°F	
DESCRIPTION:	Returns the "To Process" Temperature	

9.6 DEVID 26 & 27

The 3200 uses a single zone only (31).

Self Tuning General Purpose Temperature Controllers and General Purpose Temperature Controls support the following set of parameters.

9.6.1 ЕСНО	
POLL:	20 20
SELECT:	20 21
FORMAT:	Open – 4 Bytes
UNITS:	ASCII
DESCRIPTION:	Controller integrity command. Controller will accept and retain the data provided. The controller will provide the retained data in response to a poll enquiry.
VERSION	
POLL:	20 22
SELECT:	N/A
FORMAT:	Open 4 bytes ASCII
UNITS:	ASCII
DESCRIPTION:	SPI version command. The controller will provide a fixed SPI version number (0400 for 3200).
PROCESS SETPOINT 1	
POLL:	31 20
SELECT:	31 21
FORMAT:	Numeric
UNITS:	٥F
DESCRIPTION:	Temperature at which the process is to be maintained.
PROCESS VALUE	
POLL:	31 22
SELECT:	N/A
FORMAT:	Numeric
UNITS:	٥F
DESCRIPTION:	Present Actual Temperature of the process

PROPORTIONAL BAND 1	
POLL:	31 24
SELECT:	31 25
FORMAT:	Numeric
UNITS:	٥F
DESCRIPTION:	Proportional band for the primary control output in degrees
RESET 1 (INTEGRAL)	
POLL:	31 28
SELECT:	32 29
FORMAT:	Numeric
UNITS:	Seconds
DESCRIPTION:	Reset time for the primary control output in seconds (Integral term).
RATE 1 (DERIVATIVE)	
POLL:	31 2A
SELECT:	32 2B
FORMAT:	Numeric
UNITS:	Seconds
DESCRIPTION:	Rate time for the primary control output in seconds (Derivative term).
ALARM 1 SETPOINT	
POLL:	31 2C
SELECT:	31 2D
FORMAT:	Numeric
UNITS:	°F
DESCRIPTION:	Temperature at which the first configured 3200 alarm is activated/deactivated.
ALARM ACTIVE STATUS	
POLL:	31 2E
SELECT:	N/A
FORMAT:	Status
UNITS:	None
DESCRIPTION:	Set to '1' if there are any alarms active, otherwise 0.

ALARM 2 SETPOINT

POLL:	31 32
SELECT:	31 33
FORMAT:	Numeric
UNITS:	°F
DESCRIPTION:	Temperature at which the second configured 3200 alarm is activated/deactivated.

ALARM 1 RESET

POLL:N/ASELECT:31 35FORMAT:StatusUNITS:NoneDESCRIPTION:Write a value of 1 to acknowledge alarm conditions. Note that in the 3200, all alarms are acknowledged wh		
SELECT: 31 35 FORMAT: Status UNITS: None DESCRIPTION: Write a value of 1 to acknowledge alarm conditions. Note that in the 3200, all alarms are acknowledged whethis parameter is written to.	POLL:	N/A
FORMAT: Status UNITS: None DESCRIPTION: Write a value of 1 to acknowledge alarm conditions. Note that in the 3200, all alarms are acknowledged when this parameter is written to.	SELECT:	31 35
UNITS: None DESCRIPTION: Write a value of 1 to acknowledge alarm conditions. Note that in the 3200, all alarms are acknowledged whethis parameter is written to.	FORMAT:	Status
DESCRIPTION: Write a value of 1 to acknowledge alarm conditions. Note that in the 3200, all alarms are acknowledged wh this parameter is written to.	UNITS:	None
	DESCRIPTION:	Write a value of 1 to acknowledge alarm conditions. Note that in the 3200, all alarms are acknowledged when this parameter is written to.

ALARM 2 RESET

POLL:	N/A
SELECT:	31 37
FORMAT:	Status
UNITS:	None
DESCRIPTION:	Write a value of 1 to acknowledge alarm conditions. Note that in the 3200, all alarms are acknowledged when this parameter is written to.

LOAD CURRENT VALUE

POLL:	31 40
SELECT:	N/A
FORMAT:	Numeric
UNITS:	Amps
DESCRIPTION:	Present actual current to the load.

CONTROLLER STATUS	
POLL:	31 44
SELECT:	N/A
FORMAT:	Status
UNITS:	None
DESCRIPTION:	Instrument status.



PROCESSING	

BIT#:	0	
DESCRIPTION:	This status bit states whether this unit is currently processing.	
	0 = not currently processing (3200 manual mode)	
	1 = processing (3200 auto mode)	
MANUAL CONTROL		
BIT#:	2	
DESCRIPTION: Indicates if the control is in manual (open loop) or automatic (closed loop) control.		
	0 = Automatic Control	
	1 = Manual Control (or standby)	
LOW ALARM 1		
BIT#	3	
DESCRIPTION:	Indicates that the first configured 3200 alarm is active. For example if Alarm 1 is not configured and Alarm 2 is set to be an absolute low alarm, this bit will be set if the temperature is lower than alarm setpoint 2.	
HIGH ALARM 2		
BIT#	4	

DESCRIPTION:	Indicates that the second configured 3200 alarm is active. For example if Alarm 1 is not configured, Alarm 2 is set to be an absolute low alarm, and Alarm 3 is set to be an absolute high alarm, this bit will be set if the temperature is higher than alarm setpoint 3.	
OPEN TC ALARM		
BIT#	7	
DESCRIPTION:	Indicates an open thermocouple condition (sensor break)	
	0 = TC normal	
	1 = TC open	
SHORTED TC ALARM		
BIT#	9	
DESCRIPTION:	Indicates a shorted thermocouple condition (overrange)	
	0 = TC normal	
	1 = TC overrange	
PROCESS OUT OF CON	TROL	
BIT#	15	
DESCRIPTION:	Indicates controller is unable to maintain control of process. Requires that the 3200 'loop break time' is correctly set.	
	0 = Alarm not active	
	1 = Alarm active	
AUTOTUNE PROPORTI	IONAL BAND 1	
POLL:	31 46	
SELECT:	31 47	
FORMAT:	Numeric	
UNITS:	٥F	
DESCRIPTION:	Autotune control proportional band in degrees. Same as "Proportional Band 1" in 3200.	
AUTOTUNE RESET 1 (I	NTEGRAL)	
POLL:	31 4A	
SELECT:	32 4B	

Autotune control reset time in seconds (Integral term). Same as "Reset 1" in 3200.

FORMAT:

DESCRIPTION:

UNITS:

Numeric

Seconds

AUTOTUNE RATE 1 (DERIVATIVE)

POLL:	31 4E
SELECT:	32 4F
FORMAT:	Numeric
UNITS:	Seconds
DESCRIPTION:	Autotune control rate time in seconds (Derivative term). Same as "Rate 1" in 3200.

AUTOTUNE CONTROLS

POLL:	N/A	
SELECT:	31 55	
FORMAT:	Status	
UNITS:	None	
DESCRIPTION:	Clear autotune parameters and begin autotune.	
	0 = No action	
	1 = Clear and start tuning	

PROCESS SETPOINT 2

DESCRIPTION:	Setpoint 2: temperature at which the process is to be maintained.
UNITS:	٥F
FORMAT:	Numeric
SELECT:	31 5D
POLL:	31 5C

MANUAL PERCENT OUTPUT

POLL:	31 6A
SELECT:	31 6B
FORMAT:	Numeric
UNITS:	Percent
DESCRIPTION:	Percent of power output by the controller.

OPEN/CLOSE LOOP CONTROL

POLL:	31 8E
SELECT:	31 8F
FORMAT:	Status
UNITS:	None
DESCRIPTION: Determines if the controller is in open or closed loop of	
	0 = Open loop control (manual or standby)
	1 = Closed loop control (auto).

PROCESS TEMPERATURE DEVIATION

POLL:	31 AA
SELECT:	N/A
FORMAT:	Numeric
UNITS:	٥F
DESCRIPTION:	Plus or minus temperature deviation from setpoint in degrees

10. Remote Setpoint (Optional)

There are two inputs; 4-20mA and Volts which can be fitted in place of digital communications.

It is not necessary to fit an external burden resistor to the 4-20mA input.

If the 4-20mA remote setpoint input is connected and valid (>3.5mA; < 22mA) it will be used as the main setpoint. If it is not valid or not connected the controller will try to use the Volts input. Volts sensor break occurs at <-1; >+11V. The two inputs are not isolated from each other.

If neither remote input is valid the controller will fall back to the internal setpoint, SP1 or SP2 and flash the alarm beacon.

Be sure to set the Remote Hi Limit and Remote Lo Limit in the SETPOINT List.

11. Appendix A - Technical Specifications

Analogue Input		
	Sample rate	4Hz (250mS)
	Calibration accuracy	$\pm 0.25\%$ of reading ± 1 LSD
	Resolution	$<5, 0.5\mu V$ when using a 5 second filter
	Linearisation accuracy	<0.1% of reading
	Input filter	Off to 59.9 secs
	Zero offset	User adjustable over the full display range
	Thermocouple Types	Refer to Sensor inputs and display ranges table
	Cold junction compensation	Automatic compensation typically >30 to 1 rejection of ambient temperature change or external reference $0^{\circ}C$ (32°F)
	CJC Calibration accuracy	< <u>+</u> 1.0°C at 25°C ambient
	RTD/PT100 Type	3-wire, Pt100 DIN43760
	Bulb current	0.2mA
	Lead compensation	No error for 22 ohms in all 3 leads
	Process Linear	-10 to 80mV, 0 to 10V with external potential divider module $100 \text{K}\Omega/800$
	Current transformer	50mAac into 10 ohm. This burden resistor is fitted inside the controller
	Fusing	Fit a 2A type T fuse in line with this controller
Digital input		
	Contact closure or logic 12V @ 5-40mA	
	Contact open $>500\Omega$	
	Contact closed $< 200\Omega$	
Outputs		
Relay	Rating: 2-pin relay	Min: 12V, 100mA dc Max: 2A, 264Vac resistive
	Rating: change-over, alarm relay	Min: 12V, 100mA dc Max: 2A, 264Vac resistive
	Application	Heating, cooling, alarms or valve position
Logic	Rating	On/High 12Vdc at 5 to 44mA
	Application	Off/Low <100mV <100µA
		Heating, cooling, alarms or valve position
Triac	Current at maximum continuous operation	0.75 A rms (resistive load)
	Minimum and maximum operating voltage	30V rms to 264V rms resistive
	Snubber (22nF & 100Ω)	RC snubber must be fitted externally to prevent false triggering under line transient conditions
DC analogue output	Rating	0-20mA or 4-20mA software configurable
	Maximum load resistance	500Ω
	Isolation	Not isolated from the sensor input
	Applications	Heating, cooling or retranmission
Communications		
Digital	Transmission standard	EIA-485 2wire or EIA-232 at 1200, 2400, 4800, 9600, 19,200 baud
	Protocols	Modbus®
Control function-		2ri @
Control	Modes	PID or PI with overshoot inhibition, PD, PI, P only or On/Off or valve position
	Application	Heating and cooling
	Auto/manual	Bumpless transfer
	Setpoint rate limit	Off to 9999 degrees or display units per minute
Tuning	One-shot tune	Automatic calculation of PID and overshoot inhibition parameters
Alarms	Types	Full scale high or low. Deviation high low or hand
	Modes	Latching or non-latching. Normal or blocking action
		Up to four process alarms can be combined onto a single output
Current Transforme	er Input	r
	-	

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	Input current	0 to 50mA rms calibrated, 50/60Hz
	Scale	0 to 10, 25, 50 or 100Amps
	Input impedance	<20Ω
	Accuracy	<u>+</u> 4% of reading
	Alarms	Leakage current, overcurrent
	Indication	Custom scrolling message and beacon
	Types	High, low, deviation band, sensor fault, load leakage current, over current, internal events
Recipes		
-	Number	5
	Parameters stored	38
	Selection	Key press or via remote communications
General		
	Text Messages	10 x 30 character messages
	Dimensions and weight	48W x 48H x 90Dmm (1.89W x 1.89H x 3.54D in) 8.82oz (250g)
	Power Supply	100 to 240Vac -15%, +10%. 48 to 62Hz. 5 watts max
	Temperature and RH	Operating: 32 to 131°F (0 to 55°C), RH: 5 to 90% non-condensing.
	Storage temperature	-10 to 70°C (14 to 158°F)
	Panel sealing	IP 65, plug-in from front panel
	Safety standards	EN61010, installation category II (voltage transients must not exceed 2.5kV), pollution degree 2.
	Electromagnetic compatibility	EN61326-1 Suitable for domestic, commercial and light industrial as well as heavy industrial environments. (Class B emissions, Industrial Environment immunity).
		Low supply voltage versions are suitable for industrial environments only.
	Atmospheres	Not suitable for use above 2000m or in explosive or corrosive atmospheres.

12. Appendix B - ACS Custom Configuration Parameter List

12.1.1 Water Temp Unit

- ACS #: 724.00756.02
- Recipe Name: WAT

12.1.2 Hot Oil Unit

- ACS #: 724.00756.02
- Recipe Name: OIL

12.1.3 One Compressor Chiller – New (Effective (09/07)

- ACS #: 724.00756.02
- Recipe Name: 1CHL

12.1.4 Two Compressor Chiller – New (Effective 09/07)

- ACS #: 724.00756.02
- Recipe Name: 2CHL

12.1.5 One Compressor Chiller – Retrofit

- ACS #: 724.00789.02
- Recipe Name: 1CHR

12.1.6 Two Compressor Chiller – Retrofit

- ACS #: 724.00789.02
- Recipe Name: 2CHR

Water (TCU) ACS#: 724.00756.02



Hot Oil ACS#: 724.00756.02



1 Compressor Chiller - New ACS#: 724.00756.02



2 Compressor Chiller - New ACS#: 724.00756.02



1 Compressor Chiller - Retrofit ACS#: 724.00789.02

Recipe Name: 1CHR 10 - 1 OP - 2 AA SP CTRL ALARM TIMER RECIP CAL ACCES Input Config гELŸ гELY 5P (P, d NONE IEHF EonF ⊬ F[гELŸ d.Hı попЕ SP.SEL ЕЕГЬЯ <u>EmE</u>FG INTYP 1.I D 2.I D Ч.ТҮРЕ 8 1.TYP REE.ND PHRSE GOTO ₀FF [ŀſl[HEAF 5 LAUUC ٥F d.DUE d.out 56 ч попЕ 101 5P 1 I FUNE R 1.DHI UNITS 4.FUNC STORE LEV.2P 2.00 2.PLS гЕл СЕГГА 2.dl lo nnnn JEC.P 1.dHi 30 11 SP2 R 1.HYS LEV.3P 1.Sr [A 4.SRC.R nor 2.SENS 65 EUF 1505 ПОЛЕ nonE EnG 111 SP.HI RNG.HI 1.5rE.b 4.SRC.B PB.UNT R LLRT CONF.P 7890 - 328 ПОПЕ 30 DFF nonE 4.5RC.C по SPLO 1.5-66 R 1. BL K RNG.LO r.Tune ID dLo 0.0 NONE nonE 0 8 STD PV.OF5 1.5r E.d 4.SRC.I RM.SP R2.TYP номе PR **1.Б** FIL.T 2.00 IPL 5 **попЕ** к.соск Πο 18 Ξ лог 4.5EП5 82.JLO --R Auto nor I.SENS DFF Б По CU.TYP SP,RRT R2.HY5 COLI ΤT 1.0 ЕUF DFF m ln п STBY.T RZ.LRT SBITTP RRMPU 826 87.0 Ruto ۵ пם CJC.IN LOC.T C B.HI R2.BLK Ruto 87.0 nonE PV.IN 81.0 83.TYP 0.0 0.0 nonE MV.IN RY,TYP MR OFF **B**T 100.0 OP.HI 0.0 OP.L.O OFF D.BRND 0.0 SRFE H50 COOL.T **Я**цЕо ^{я--м} optional l.D RIJIRESS Πο LBR

2 Compressor Chiller - Retrofit

ACS#: 724.00789.02 Recipe Name: 2CHR OP - 2 ALARM TIMER RECIP ACCES AA Config SP CTRL CAL Config Input IO - 1 Config Config Config Config Config Config Config Config Config SP 1 SP.SEL гЕLЧ 1.13 Рі І СЕГСН NONE E∞£FG 5C.HL ⊬ £[гELY гELY nonE nonE EonF INTYP Ч.Т ҮРЕ R 1.TYP PHASE 2.I D REC.NO 6010 OFF Elfle ٩P d.out HEAF d.DUE 56 nonE попЕ 5P 1 I FUNC 2 FUNC UNITS 4,FUNC 82.TYP STORE LEV.2P Э.dHI 2.5-с.Я 2.00 IPLS ЧĤ H.dHl 30 гЕи СЕГLЯ пппп 5P2 LEV.3P DEC.P 4.SRC.R 8<u>3.</u>TYP 1505 ПОПЕ EnG nor I.SENS попЕ 65 2 SP.HI 2.5rE.b R3.DHI . CONF.P RNG,HI 4.SRC.1 PB.UNT NDNE 2.5r C.C - 328 nonE 30 DFF Ч 7890 SPLD RNG.LO 4.SRC.C r.Tune R3.HYS ID ПОЛЕ 2.5-С.d EUF TMR (7) 0.0 ۵ Ч nonE RM.SP PV.DFS 4.SRC.I PR R3.LRT номе **по** R3.BLK 1.6 По 18 nonE nor 2.5ENS пог 4.5EЛ5 FIL.T ---R K.LOEK Ruto DFF dНı CJ.TYP SP,RRT RY, TYP COLI ΤD **ם ה** SB,TYP 1.0 *А*Ь5,Я m ln 2 RRMPU R2G RY.IHI STBY.T 87.0 Ruto 5 0 EJE.IN LOC.T R4,H Y S C B.HI EUE RYLET Ruto 87.0 PV.IN C B.LO

10 1

11

111

По

0.0 MV.IN



0.0 OP.LO

0.0

DFF L₿T

по

RY.BLK



По LBR

optional 1.0 RIJRESS